

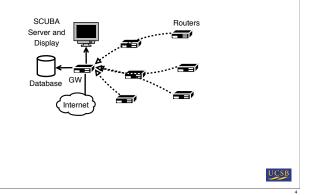
## Scenario

- Large-scale metro-mesh wireless networks
  - Hundreds of repeaters, tens of gateways
  - Thousands of mobile and home users
  - Examples:
    - ~500 nodes in the Google WiFi
  - ~100 nodes in the Meraki SF Network
- Diagnosing performance is hard
  - Multitude of metrics
  - Graphs and plots are tedious
  - Time-consuming and exhausting



# SCUBA

- What is SCUBA?
  - Visualization framework to diagnose mesh network performance



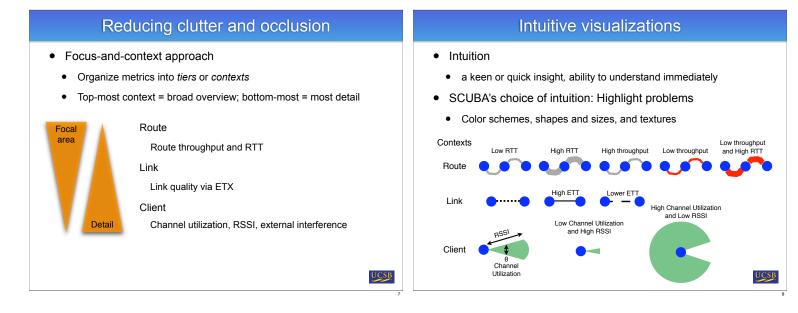
# SCUBA

- What is SCUBA?
  - Visualization framework to diagnose mesh network performance
- Design goals
  - Reduced clutter and occlusion
  - Intuitive visualization
  - Interactive interface
  - Selectable modalities
- Impact
  - Fast and efficient diagnosis
  - Better diagnostic framework design

## Outline

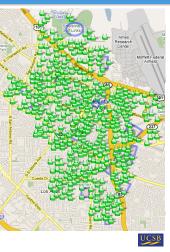
- Reduced clutter and occlusion
  - Focus and context approach via tiers of metrics
- Intuitive visualization
  - Choice of color schemes, sizes, shapes, and textures
- Interactive interface
  - Zooming and focussing
- Selectable modalities
- Planar and hyperbolic views
- Implementation on the UCSB MeshNet
- Future work

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# Sample network

- Google WiFi
  - 425 routers, 66 gateways
  - ~2000 clients per day
- Tailored data
  - ETX is proportional to distance
- Routes are shortest paths to closest gateways
- Random number of clients per node
- Route throughput and RTT is based on number of hops + some randomness



## Visualization examples

-ND-138

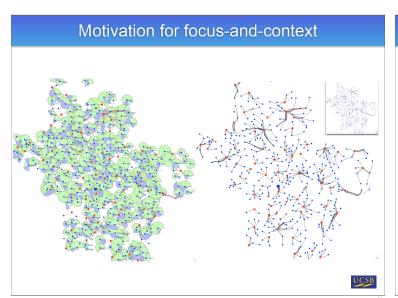
throughput = 1.3 delay = 20.42 hops = 2

-ND-152

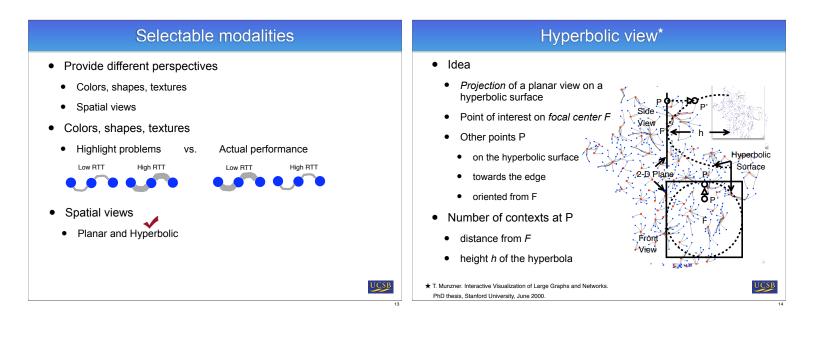
00:32:65:51:19:f6

37.16% utilization -20.0dB signal

- Route and link contexts
  - Routes are curved lines from routers to GWs
  - Links are straight lines between nodes
  - Metrics displayed on mouse-overs
- Client context
  - Circle sectors represent a client
  - Client metrics displayed on mouse-overs

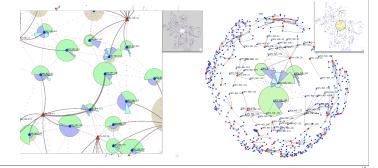


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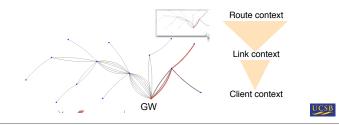
## Views trade-off

- Planar view
  - Preserves geographic location and orientation of nodes
- Hyperbolic view
- · Preserves global view and automatically adjusts contexts



## SCUBA on the UCSB MeshNet

- UCSB MeshNet
  - 15 nodes (14 repeaters and 1 gateway) on three floors
  - Metrics from each node stored in a SQL database
  - SCUBA reads metrics from the database
- Problem diagnosis
- Artificial problem client introduced



## Conclusions

- · As networks grow larger, diagnosis becomes harder
  - Good visualization tools are important
  - Research on key metrics and visualization is necessary
- Scuba is a diagnostic framework
  - Metrics organization and interaction with visuals
  - Eases diagnosis
- Future of large-scale complex metro networks
- Auto-diagnostic tools and protocols will become very useful
- Scuba is a means of diagnosis as well as planning

# Future work

- Additional dimensions
  - Time to diagnose temporal problems such as flash-crowds
  - 3D Scuba to use the height as another information descriptor
- SCUBA and the collection of metrics
  - Focus-and-context used to control when/which metrics are collected
- Qualitative study of SCUBA usability
  - How useful is SCUBA in a variety of scenarios?
- Auto-focus on problems
  - Use of thresholds and temporal changes to self-identify problems

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Quantitative study for speed and accuracy of diagnosis

# Questions?

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- SCUBA: Focus and Context for Mesh Health Diagnosis
  - Contact: amitj@cs.ucsb.edu or mock@cs.ucsb.edu
- Video demo of SCUBA on
  - http://moment.cs.ucsb.edu/conan/scuba
- 3D version of SCUBA and code
  - http://cs.ucsb.edu/~mock/netvisual/for290i/